

Separable Transformation

G is separable if

$$O(f) = A f B \quad \text{for some matrix } A, B.$$

Remark

$$\begin{aligned} \vec{f}_i &: i\text{-th col} & A f &= A \left[\vec{f}_1 \mid \dots \mid \vec{f}_n \right] \\ & & &= \left[A \vec{f}_1 \mid \dots \mid A \vec{f}_n \right] \end{aligned}$$

\vec{f}'_j : j -th row

\therefore Operation on Columns

$$\begin{aligned} f B &= \left[\begin{array}{c|ccc} - & \vec{f}_1 & - & - \\ - & \vec{f}_2 & - & - \\ \vdots & \vdots & \vdots & \vdots \\ - & \vec{f}_n & - & - \end{array} \right] B \\ &= \left[\begin{array}{ccc|c} - & \vec{f}'_1 B & - & \\ \vdots & \vdots & \vdots & \\ - & \vec{f}'_n B & - & \end{array} \right] \end{aligned}$$

\therefore Operation on rows

\vec{f} is called separable as it can be separated into operations on rows and columns.

Example

Suppose a Transformation Matrix:

$$H = \begin{bmatrix} 2 & 0 & 8 & 0 \\ 1 & 2 & 4 & 8 \\ 6 & 0 & 4 & 0 \\ 3 & 6 & 2 & 4 \end{bmatrix}$$

Block Matrix Multiplication

A_i, B_j are matrices

$$A = \begin{bmatrix} A_1 & A_3 \\ A_2 & A_4 \end{bmatrix}, B = \begin{bmatrix} B_1 & B_3 \\ B_2 & B_4 \end{bmatrix} \quad \text{are block matrices}$$

$$AB = \begin{bmatrix} A_1 B_1 + A_3 B_2 & A_1 B_3 + A_3 B_4 \\ A_2 B_1 + A_4 B_2 & A_2 B_3 + A_4 B_4 \end{bmatrix}$$

Provided that all matrix multiplications
and additions are make sense

$$g = Hf = \begin{bmatrix} 2 & 0 & 8 & 0 \\ 1 & 2 & 4 & 8 \\ 6 & 0 & 4 & 0 \\ 3 & 6 & 2 & 4 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix} & 4 \begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix} \\ 3 \begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix} & 2 \begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} f_1 \\ f_2 \end{bmatrix} \\ \begin{bmatrix} f_3 \\ f_4 \end{bmatrix} \end{bmatrix}$$

$= A$

$$g = \begin{bmatrix} 1 A \begin{bmatrix} f_1 \\ f_2 \end{bmatrix} + 4 A \begin{bmatrix} f_3 \\ f_4 \end{bmatrix} \\ 3 A \begin{bmatrix} f_1 \\ f_2 \end{bmatrix} + 2 A \begin{bmatrix} f_3 \\ f_4 \end{bmatrix} \end{bmatrix}$$

reshape ↓

$$g = \begin{bmatrix} 1 A \begin{bmatrix} f_1 \\ f_2 \end{bmatrix} + 4 A \begin{bmatrix} f_3 \\ f_4 \end{bmatrix} & 3 A \begin{bmatrix} f_1 \\ f_2 \end{bmatrix} + 2 A \begin{bmatrix} f_3 \\ f_4 \end{bmatrix} \end{bmatrix}$$

$$= A \begin{bmatrix} f_1 & f_3 \\ f_2 & f_4 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix}$$

∴ Separable, $O(f) = \begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix} + \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix}$

Frobenius Norm

$$A \in \mathbb{R}^{N \times N}$$

$$\|A\|_F := \sqrt{\sum_{1 \leq i, j \leq N} |a_{ij}|^2}$$

$\|A - B\|_F$ can be a measure of similarity between A and B .

e.g.

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 1 & 1 \\ \vdots & \vdots & \vdots \\ 1 & 1 & 1 \end{bmatrix}$$

Find α s.t. $\|A - \alpha B\|_F$ is minimized.

Note minimizing $\|A - \alpha B\|_F$

\Leftrightarrow minimizing $\|A - \alpha B\|_F^2$

$$\|A - \alpha B\|_F^2 = \sum_{1 \leq i, j \leq 3} (a_{ij} - \alpha)^2$$

$$\frac{\partial}{\partial \alpha} \|A - \alpha B\|_F^2 = \sum_{1 \leq i, j \leq 3} 2(\alpha - a_{ij})$$

$$\frac{\partial}{\partial \alpha} \|A - \alpha B\|_F^2 = 0$$

$$\Leftrightarrow 3^2 \alpha = \sum_{1 \leq i, j \leq 3} a_{ij} \Leftrightarrow \alpha = \frac{1}{9} \sum_{1 \leq i, j \leq 3} a_{ij}$$

$\therefore \alpha$ is the average of values of A .

SVD

$$A \in \mathbb{R}^{M \times N}$$

A can be decomposed to:

$$A = U \bar{\Sigma} V^T$$

where $U \in \mathbb{R}^{M \times M}$, orthogonal

$\bar{\Sigma} \in \mathbb{R}^{M \times N}$, non-negative diagonal,

0 elsewhere

$V \in \mathbb{R}^{N \times N}$, orthogonal

Example

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

Note $A = U \bar{\Sigma} V^T$

$$\begin{aligned} A A^T &= (U \bar{\Sigma} V^T)(V \bar{\Sigma}^T U^T) \\ &= U (\bar{\Sigma} \bar{\Sigma}^T) U^T \end{aligned}$$

$$\begin{aligned} A^T A &= (V \bar{\Sigma}^T U^T)(U \bar{\Sigma} V^T) \\ &= V (\bar{\Sigma}^T \bar{\Sigma}) V^T \end{aligned}$$

where $\bar{\Sigma} \bar{\Sigma}^T$, $\bar{\Sigma}^T \bar{\Sigma}$ are
diagonal square matrix.

So finding the diagonalization of
 $A^T A$ and $A A^T$ gives us SVD.

To find Eigenvectors and Eigenvalues of $A A^T$:

$$A A^T = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

$$0 = \det(A A^T - \lambda I) = (2 - \lambda)^2 - 1$$

$$0 = \lambda^2 - 4\lambda + 3$$

$$\Leftrightarrow 0 = (\lambda - 1)(\lambda - 3)$$

$$\Leftrightarrow \lambda = 3 \text{ or } \lambda = 1.$$

$\lambda = 3$:

$$\begin{bmatrix} 2-3 & 1 \\ 1 & 2-3 \end{bmatrix} \xrightarrow{RRE\bar{F}} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}$$

$$\therefore \text{eigenvector} = a_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\lambda = 1:$$

$$\begin{bmatrix} 2-1 & 1 \\ 1 & 2-1 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$

$$\therefore \text{eigenvector} = a_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\text{Normalizing, } U = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix}$$

$$\text{with } \Sigma = \begin{bmatrix} \sqrt{3} & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$A = U \Sigma V^T$$

\vec{u}_i : i -th col of U

$$U^T A = \Sigma V^T$$

\vec{v}_j : j -th of V

$$\begin{bmatrix} -\vec{u}_1^T \\ -\vec{u}_2^T \end{bmatrix} A = \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \end{bmatrix} \begin{bmatrix} -\vec{v}_1^T \\ -\vec{v}_2^T \\ -\vec{v}_3^T \end{bmatrix}$$

$$\begin{bmatrix} -(A^T \vec{u}_1)^T \\ -(A^T \vec{u}_2)^T \end{bmatrix} = \begin{bmatrix} -\sigma_1 \vec{v}_1^T \\ -\sigma_2 \vec{v}_2^T \end{bmatrix}$$

$$\therefore \vec{v}_1 = \frac{1}{\sigma_1} A^T \vec{u}_1, \quad \vec{v}_2 = \frac{1}{\sigma_2} A^T \vec{u}_2$$

$$\begin{aligned} \vec{v}_1 &= \frac{1}{\sqrt{3}} \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} \\ &= \begin{bmatrix} 1/\sqrt{6} \\ \sqrt{2/3} \\ 1/\sqrt{6} \end{bmatrix} \end{aligned}$$

$$\vec{v}_2 = \frac{1}{1} \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{bmatrix}$$

$$= \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ -1/\sqrt{2} \end{bmatrix}$$

\vec{v}_3 can be calculated by cross product:

$$\vec{v}_3 = \vec{v}_1 \times \vec{v}_2$$

$$= \det \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1/\sqrt{6} & \sqrt{2}/3 & 1/\sqrt{6} \\ 1/\sqrt{2} & 0 & -1/\sqrt{2} \end{bmatrix}$$

$$= \begin{bmatrix} -1/\sqrt{3} \\ 1/\sqrt{3} \\ -1/\sqrt{3} \end{bmatrix}$$

$$\therefore A = U \Sigma V^T$$

$$\text{where } U = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix}$$

$$\Sigma = \begin{bmatrix} \sqrt{3} & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$V = \begin{bmatrix} 1/\sqrt{6} & 1/\sqrt{2} & -1/\sqrt{3} \\ \sqrt{2}/3 & 0 & 1/\sqrt{3} \\ 1/\sqrt{6} & -1/\sqrt{2} & -1/\sqrt{3} \end{bmatrix}$$